Formal Languages, Automata and Codes

Oleg Gutik

Lecture 1

1 INTRODUCTION TO THE THEORY OF COMPUTATION

In this part of preliminary lectures, we give an account of some basic notions which will be used throughout our course "**Formal Languages, Automata and Codes**".

A *set* is a collection of elements, without any structure other than membership. To indicate that x is an element of the set S, we write $x \in S$. The statement that x is not in S is written $x \notin S$. A set can be specified by enclosing some description of its elements in curly braces; for example, the set of integers $0, 1, 2$ is shown as

$$S = \{0, 1, 2\}.$$

Ellipses are used whenever the meaning is clear. Thus, $\{a, b, \ldots, z\}$ stands for all the lowercase letters of the English alphabet, while $\{2, 4, 6, \ldots\}$ denotes the set of all positive even integers. When the need arises, we use more explicit notation, in which we write

$$S = \{i \colon i > 0, i \text{ is even}\} \tag{1}$$

for the last example. We read this as "S is the set of all i, such that i is greater than zero, and i is even," implying, of course, that i is an integer.

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The usual set operations are *union* ($\cup$), *intersection* ($\cap$), and *difference* ($-$ or $\backslash$) defined as

$$S_1 \cup S_2 = \{x \colon x \in S_1 \text{ or } x \in S_2\},$$
$$S_1 \cap S_2 = \{x \colon x \in S_1 \text{ and } x \in S_2\},$$
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Another basic operation is *complementation*. The *complement* of a set S, denoted by $\overline{S}$, consists of all elements which are not in S. To make this meaningful, we need to know what the universal set U of all possible elements is. If U is specified, then

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The set with no elements, called the *empty set* or the *null set*, is denoted by $\varnothing$. From the definition of a set, it is obvious that

$$S \cup \varnothing = S - \varnothing = S,$$
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The following useful identities, known as *DeMorgan's laws*,

$$\overline{S_1 \cup S_2} = \overline{S}_1 \cap \overline{S}_2, \quad (2)$$

$$\overline{S_1 \cap S_2} = \overline{S}_1 \cup \overline{S}_2. \quad (3)$$

are needed on several occasions.

A set S_1 is said to be a *subset* of S if every element of S_1 is also an element of S. We write this as

$$S_1 \subseteq S.$$

If $S_1 \subseteq S$, but S contains an element not in S_1, we say that S_1 is a *proper subset* of S; we write this as

$$S_1 \subset S.$$

If the sets S_1 and S_2 have no common element, that is, $S_1 \cap S_2 = \varnothing$, then the sets S_1 and S_2 are said to be *disjoint*.

A set is said to be *finite* if it contains a finite number of elements; otherwise it is infinite. The size of a finite set is the number of elements in it; this is denoted by $|S|$.

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Example 1.1

If $S = \{a, b, c\}$, then its powerset is

$$2^S = \{\varnothing, \{a\}, \{b\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}, \{a, b, c\}\}.$$

Here $|S| = 3$ and $\left|2^S\right| = 8$. This is an instance of a general result; if S is finite, then

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Note that the order in which the elements of a pair are written matters. The pair $(4, 2)$ is in $S_1 \times S_2$, but $(2, 4)$ is not.

This notation is extended in an obvious fashion to the Cartesian product of more than two sets; generally

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$$S = S_1 \times S_2 = \{(x, y) : x \in S_1, y \in S_2\}.$$

Example 1.2

Let $S_1 = \{2, 4\}$ and $S_2 = \{2, 3, 5, 6\}$. Then

$$S_1 \times S_2 = \{(2,2), (2,3), (2,5), (2,6), (4,2), (4,3), (4,5), (4,6)\}.$$

Note that the order in which the elements of a pair are written matters. The pair $(4, 2)$ is in $S_1 \times S_2$, but $(2, 4)$ is not.

This notation is extended in an obvious fashion to the Cartesian product of more than two sets; generally

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A set can be divided by separating it into a number of subsets. Suppose that $S_1, S_2, \ldots, S_n$ are subsets of a given set S and that the following holds:

1) the subsets $S_1, S_2, \ldots, S_n$ are mutually disjoint;

2) $S_1 \cup S_2 \cup \cdots \cup S_n = S$;

3) every of S_i is nonempty.

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A *function* is a rule that assigns to elements of one set a unique element of another set. If f denotes a function, then the first set is called the *domain* of f, and the second set is its *range*. We write

$$f : S_1 \to S_2$$

to indicate that the domain of f is a subset of S_1 and that the range of f is a subset of S_2. If the domain of f is all of S_1, we say that f is a *total function* on S_1; otherwise f is said to be a *partial function*.

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In many applications, the domain and range of the functions involved are in the set of positive integers. Furthermore, we are often interested only in the behavior of these functions as their arguments become very large. In such cases an understanding of the growth rates may suffice and a common order of magnitude notation can be used. Let $f(n)$ and $g(n)$ be functions whose domain is a subset of the positive integers. If there exists a positive constant c such that for all sufficiently large n

$$f(n) \leq c|g(n)|,$$

we say that f *has order at most* g. We write this as

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In many applications, the domain and range of the functions involved are in the set of positive integers. Furthermore, we are often interested only in the behavior of these functions as their arguments become very large. In such cases an understanding of the growth rates may suffice and a common order of magnitude notation can be used. Let $f(n)$ and $g(n)$ be functions whose domain is a subset of the positive integers. If there exists a positive constant c such that for all sufficiently large n

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Example 1.3

Let

$$f(n) = 2n^2 + 3n,$$
$$g(n) = n^3,$$
$$h(n) = 10n^2 + 100.$$

Then

$$f(n) = O(g(n)),$$
$$g(n) = \Omega(h(n)),$$
$$f(n) = \Theta(h(n)).$$

In order-of-magnitude notation, the symbol $=$ should not be interpreted as equality and order-of-magnitude expressions cannot be treated like ordinary expressions. Manipulations such as

$$O(n) + O(n) = 2O(n)$$

are not sensible and can lead to incorrect conclusions. Still, if used properly, the order-of-magnitude arguments can be effective, as we will see in later lectures.

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$$x \equiv y.$$

A relation denoted by $\equiv$ is considered an equivalence if it satisfies three rules: the reflexivity rule

$$x \equiv x \text{ for all } x;$$

the symmetry rule

$$\text{if } x \equiv y, \text{ then } y \equiv x;$$

and the transitivity rule

$$\text{if } x \equiv y \text{ and } y \equiv z, \text{ then } x \equiv z.$$

Some functions can be represented by a set of pairs

$$\{(x_1, y_1), (x_2, y_2), \ldots\},$$

where x_i is an element in the domain of the function, and y_i is the corresponding value in its range. For such a set to define a function, each x_i can occur at most once as the first element of a pair. If this is not satisfied, the set is called a *relation*. Relations are more general than functions: In a function each element of the domain has exactly one associated element in the range; in a relation there may be several such elements in the range.
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Example 1.4

On the set of nonnegative integers, we can define a relation

$$x \equiv y$$

if and only if

$$x \mod 3 = y \mod 3.$$

Then $2 \equiv 5$, $12 \equiv 0$, and $0 \equiv 36$. Clearly this is an equivalence relation, as it satisfies reflexivity, symmetry, and transitivity.

If S is a set on which we have a defined equivalence relation, then we can use this equivalence to partition the set into equivalence classes. Each equivalence class contains all and only equivalent elements.

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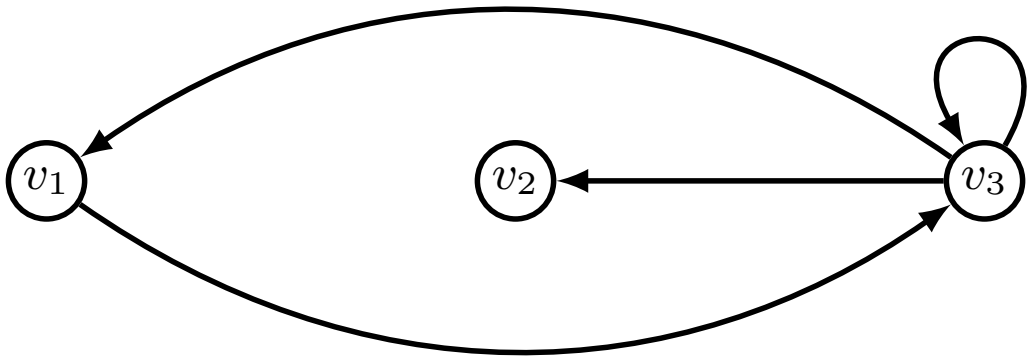

A sequence of edges $(v_i, v_j), (v_j, v_k), \ldots, (v_m, v_n)$ is said to be a *walk* from v_i to v_n. The *length of a walk* is the total number of edges traversed in going from the initial vertex to the final one. A walk in which no edge is repeated is said to be a *path*; a path is *simple* if no vertex is repeated. A walk from v_i to itself with no repeated edges is called a *cycle with base* v_i. If no vertices other than the base are repeated in a cycle, then it is said to be *simple*. In the Figure, $(v_1, v_3), (v_3, v_2)$ is a simple path from v_1 to v_2.

The sequence of edges $(v_1, v_3), (v_3, v_3), (v_3, v_1)$ is a cycle, but not a simple one. If the edges of a graph are labeled, we can talk about the label of a walk. This label is the sequence of edge labels encountered when the path is traversed. Finally, an edge from a vertex to itself is called a *loop*. In the Figure, there is a loop on vertex v_3.

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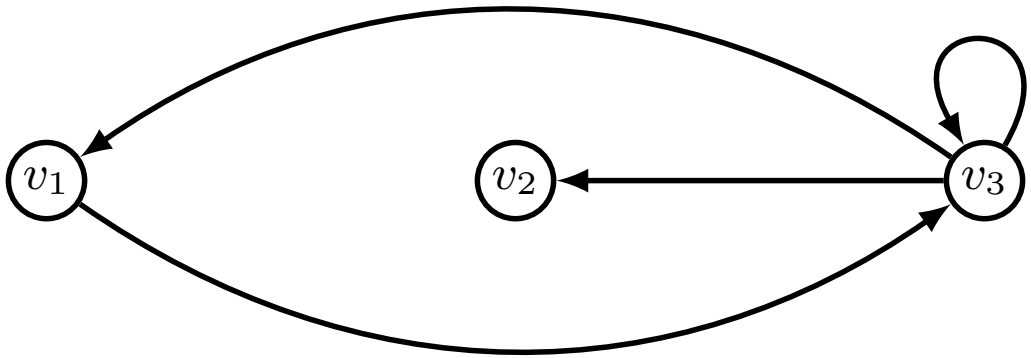

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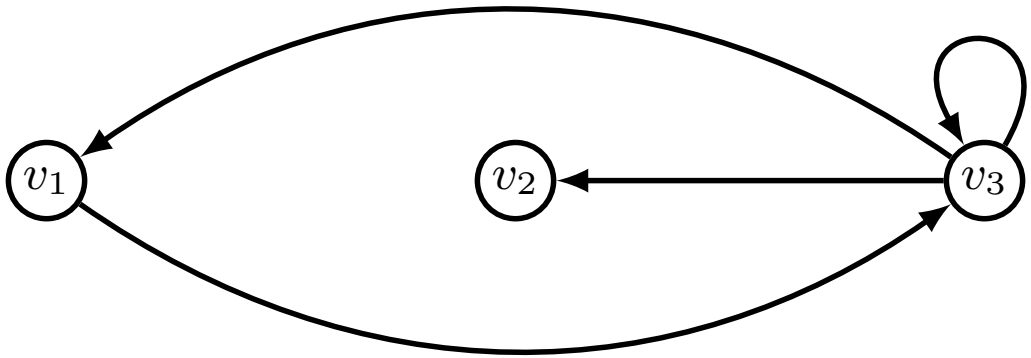

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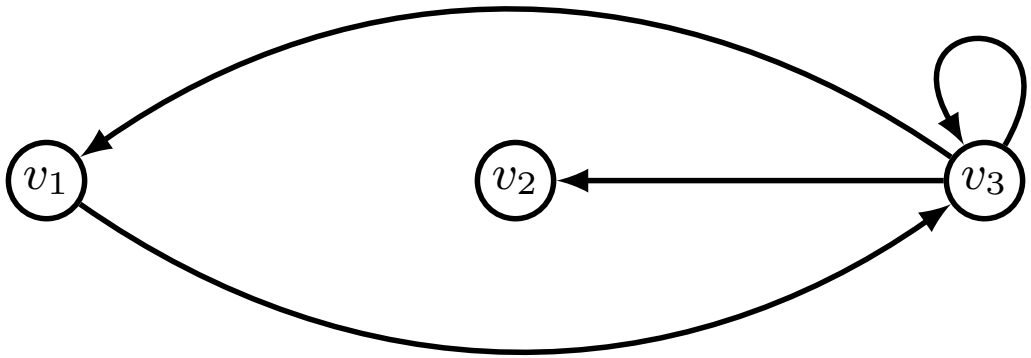

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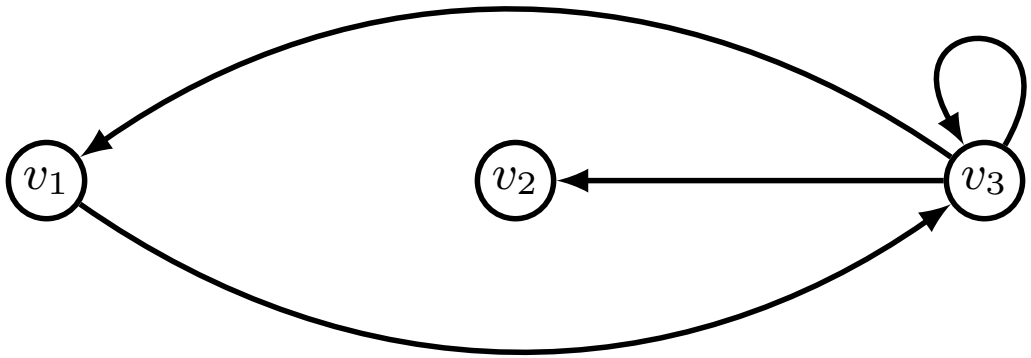

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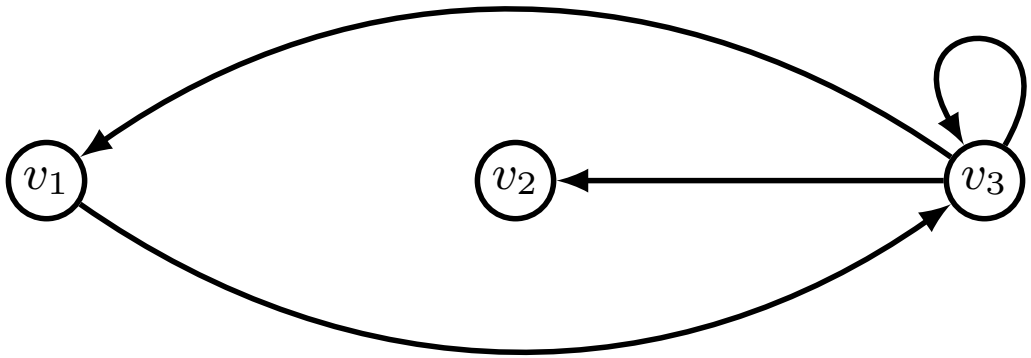

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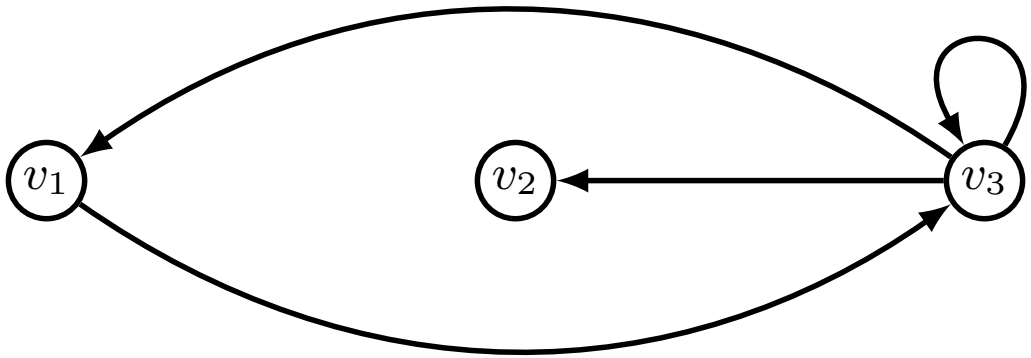

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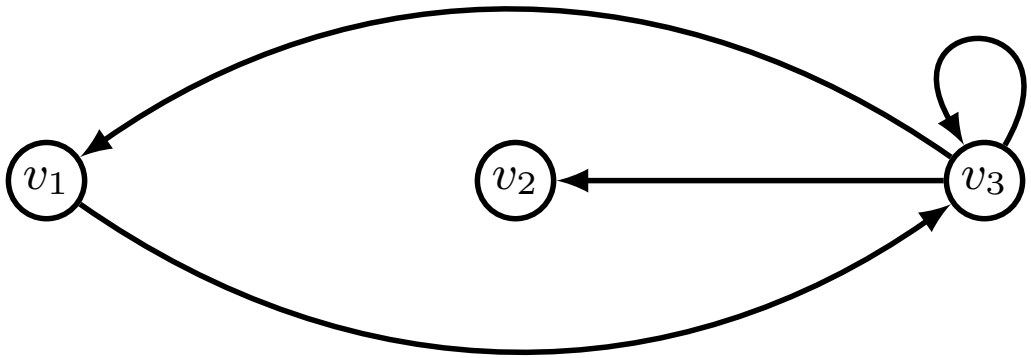

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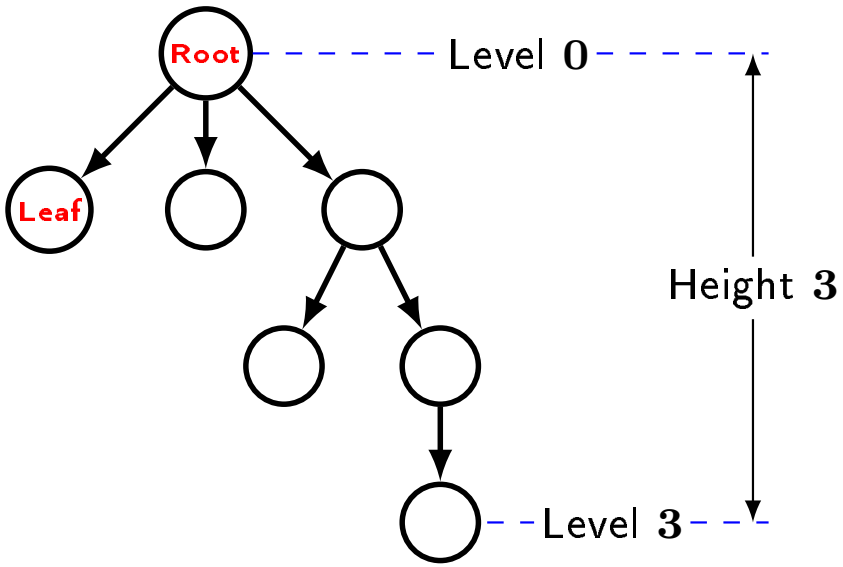

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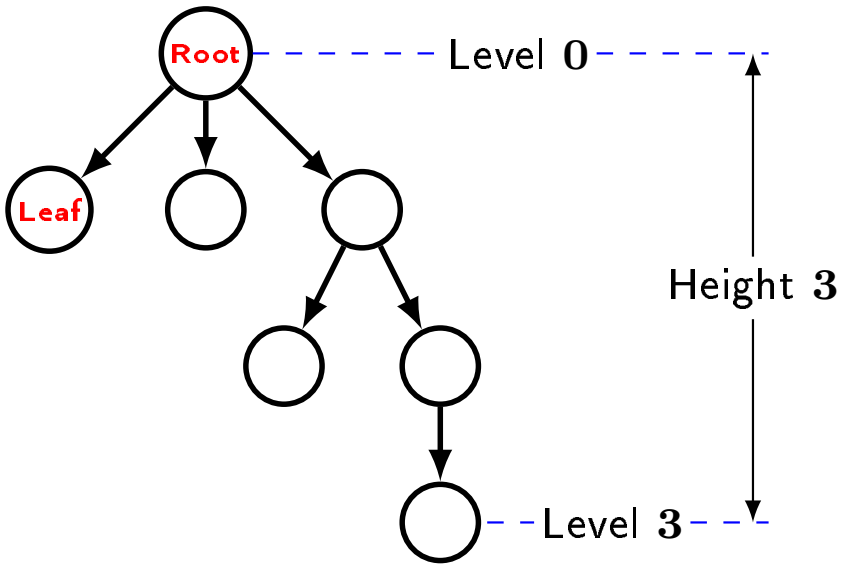

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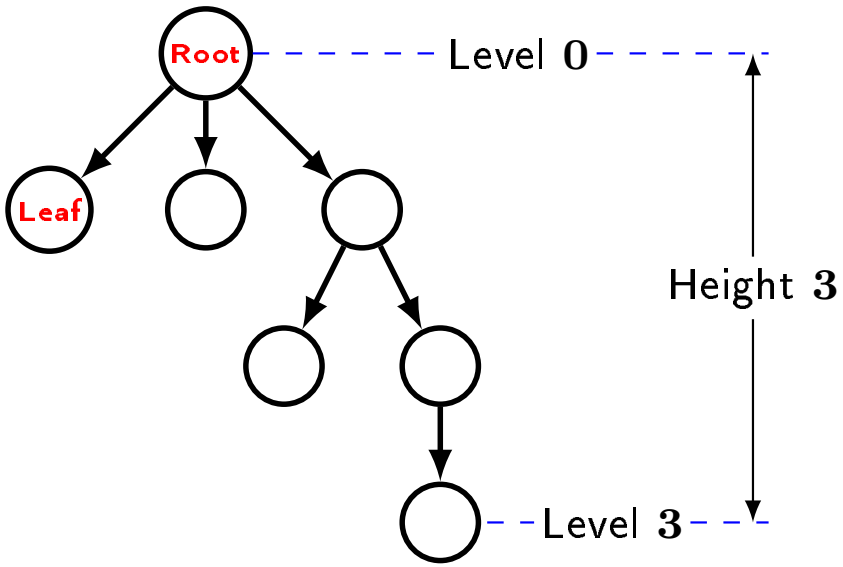

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The starting statements $P_1, P_2, \ldots, P_k$ are called the basis of the induction. The step connecting P_n with P_{n+1} is called the *inductive step*. The inductive step is generally made easier by the inductive assumption that $P_1, P_2, \ldots, P_n$ are true, then argue that the truth of these statements guarantees the truth of P_{n+1}. In a formal inductive argument, we show all three parts explicitly.

1. For some $k \geq 1$, we know that $P_1, P_2, \ldots, P_k$ are true.
2. The problem is such that for any $n \geq k$, the truths of $P_1, P_2, \ldots, P_n$ imply the truth of P_{n+1}.

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Example 1.5

A binary tree is a tree in which no parent can have more than two children. Prove that a binary tree of height n has at most 2^n leaves.

Proof: If we denote the maximum number of leaves of a binary tree of height n by $l(n)$, then we want to show that $l(n) \leq 2^n$.

Basis: Clearly $l(0) = 1 = 2^0$, because a tree of height 0 can have no nodes other than the root, that is, it has at most one leaf.

Inductive Assumption:

$$l(i) \leq 2^i, \quad \text{for } i = 0, 1, \ldots, n. \tag{4}$$

Inductive Step: To get a binary tree of height $n+1$ from one of height n, we can create, at most, two leaves in place of each previous one. Therefore,

$$l(n+1) = 2l(n).$$

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Inductive Assumption:

$$l(i) \leq 2^i, \quad \text{for } i = 0, 1, \ldots, n. \tag{4}$$

Inductive Step: To get a binary tree of height $n+1$ from one of height n, we can create, at most, two leaves in place of each previous one. Therefore,

$$l(n+1) = 2l(n).$$

Now, using the inductive assumption, we get that

$$l(n+1) \leq 2 \cdot 2^n = 2^{n+1}.$$

Thus, if our claim is true for n, it must also be true for $n+1$. Since n can be any number, the statement must be true for all n. ■

Here we introduce the symbol ■ that is used in our course of lectures to denote the end of a proof.

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A binary tree is a tree in which no parent can have more than two children. Prove that a binary tree of height n has at most 2^n leaves.

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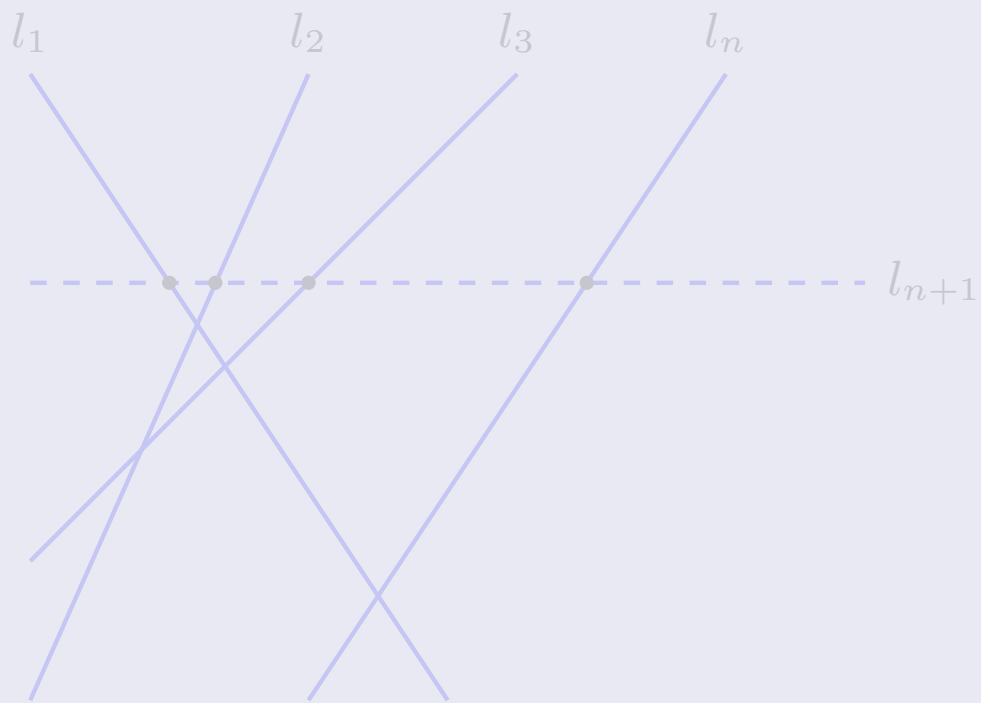
Example 1.6

A set $l_1, l_2, \ldots, l_n$ of mutually intersecting straight lines divides the plane into a number of separated regions. A single line divides the plane into two parts, two lines generate four regions, three lines make seven regions, and so on. This is easily checked visually for up to three lines, but as the number of lines increases it becomes difficult to spot a pattern. Let us try to solve this problem recursively.

Look at the Figure to see what happens if we add a new line l_{n+1} to existing n lines.



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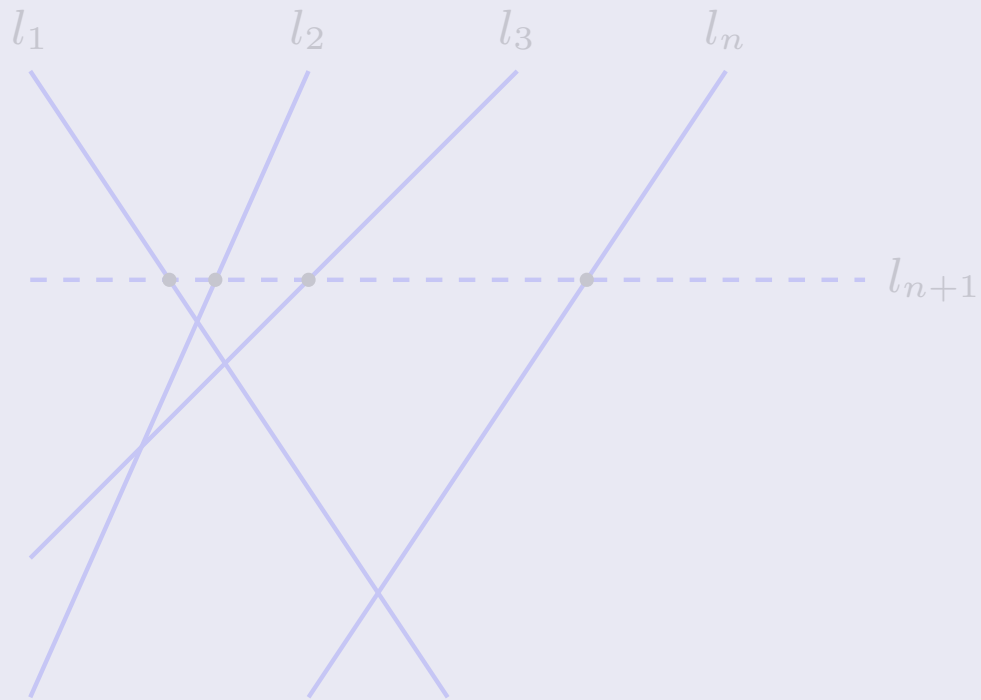

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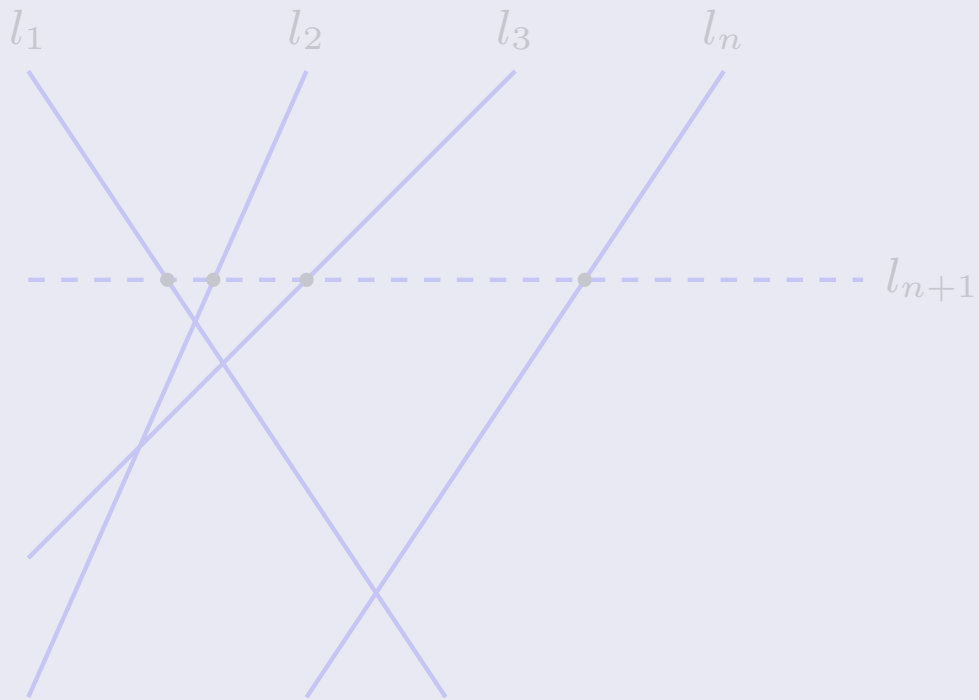

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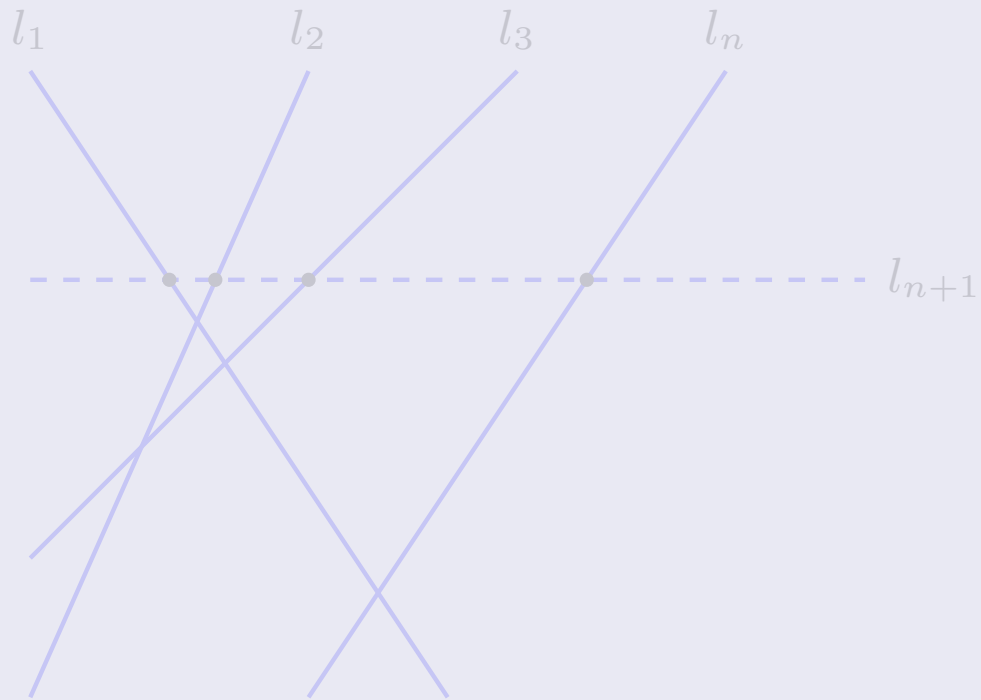

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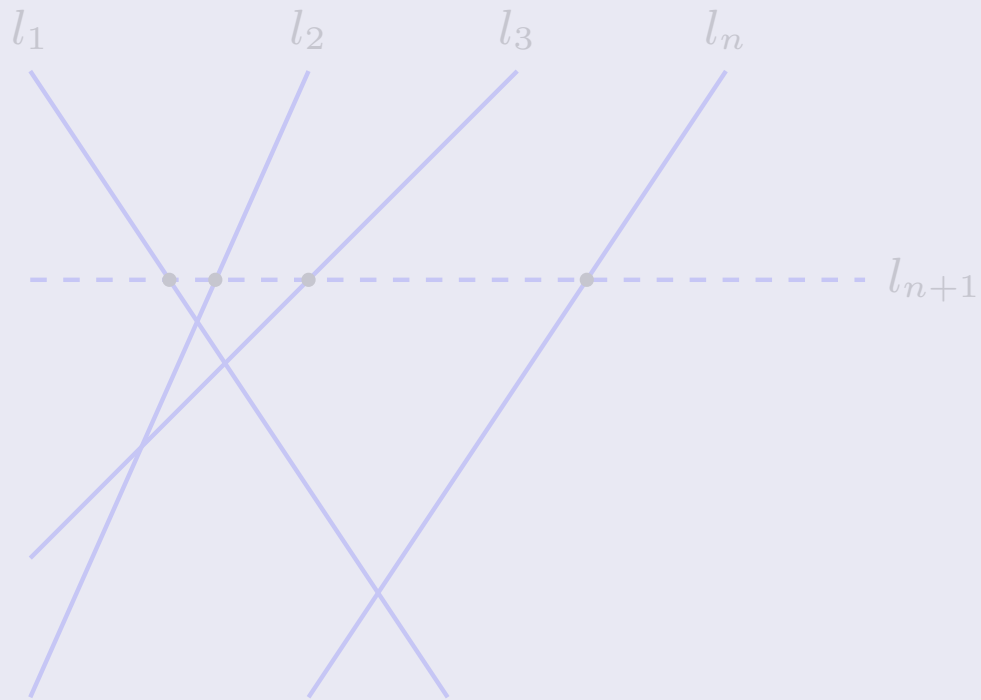

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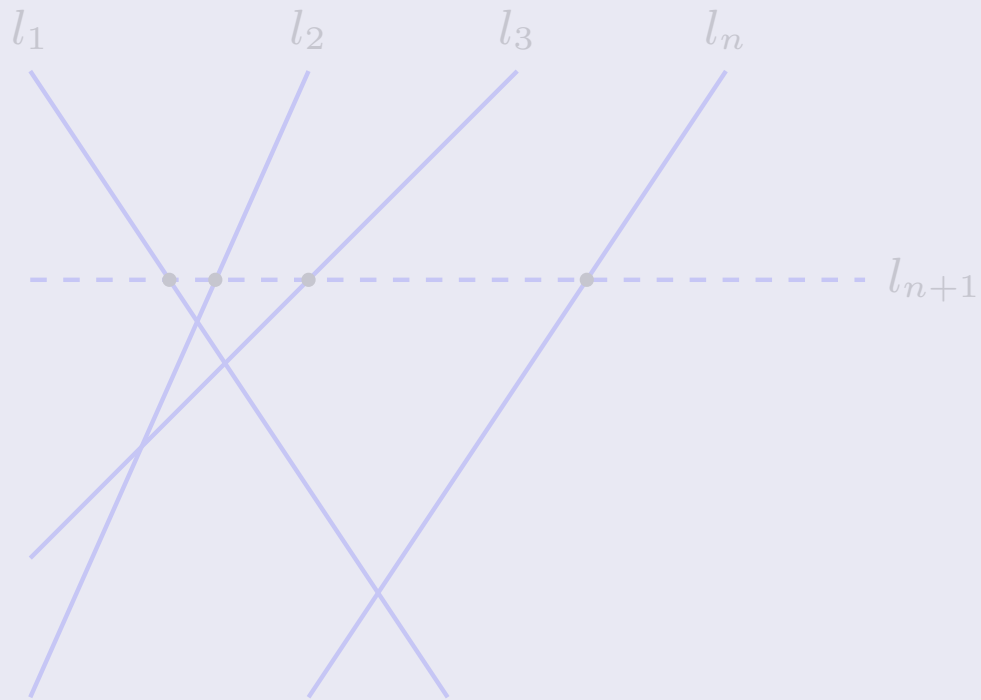

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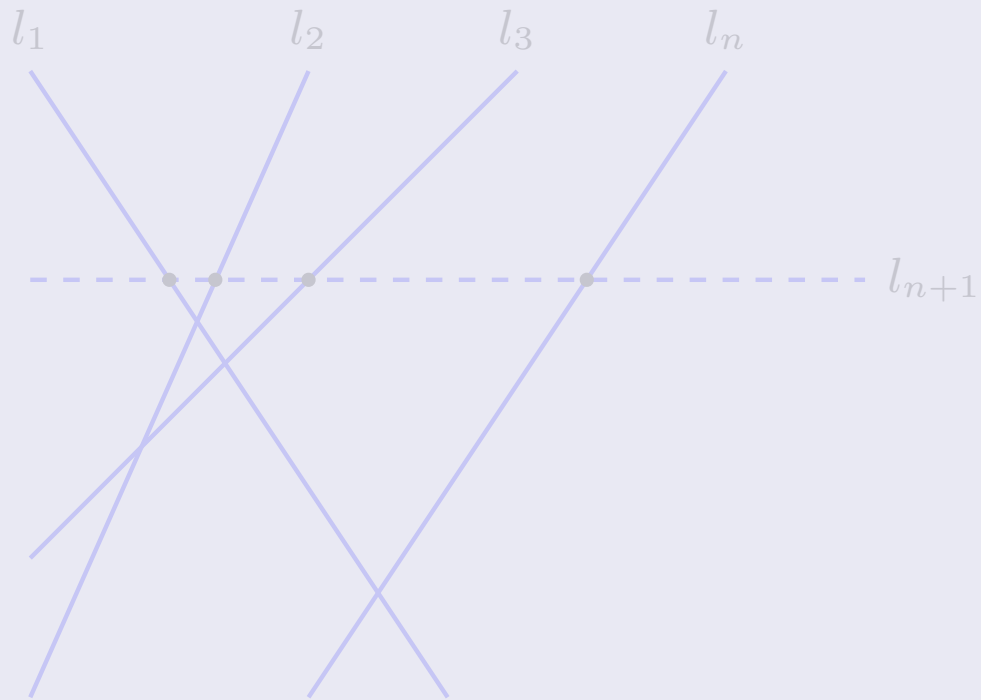

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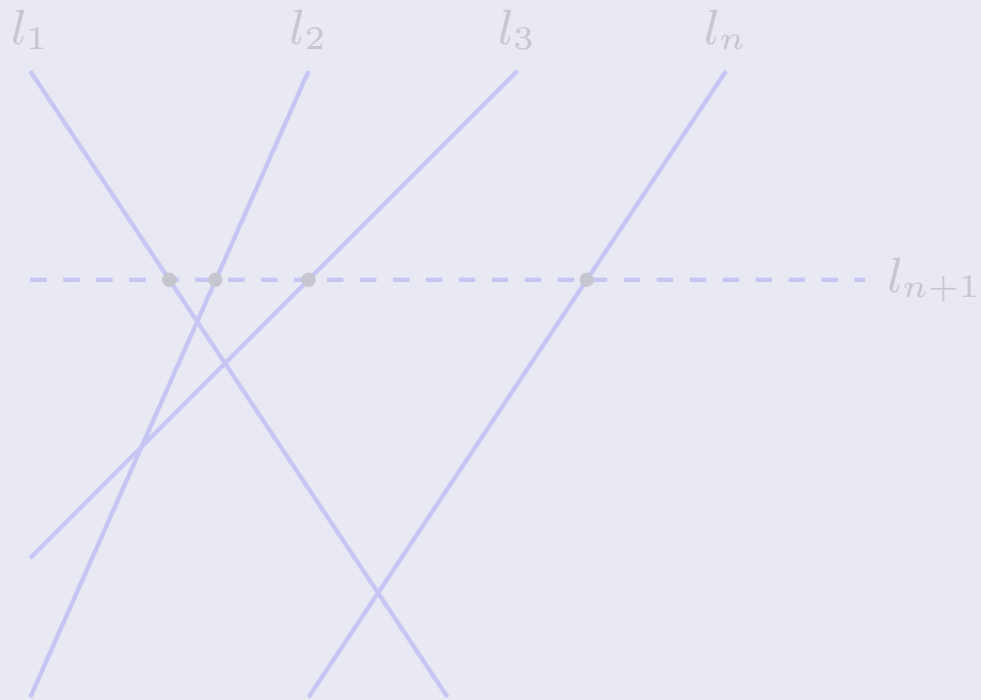

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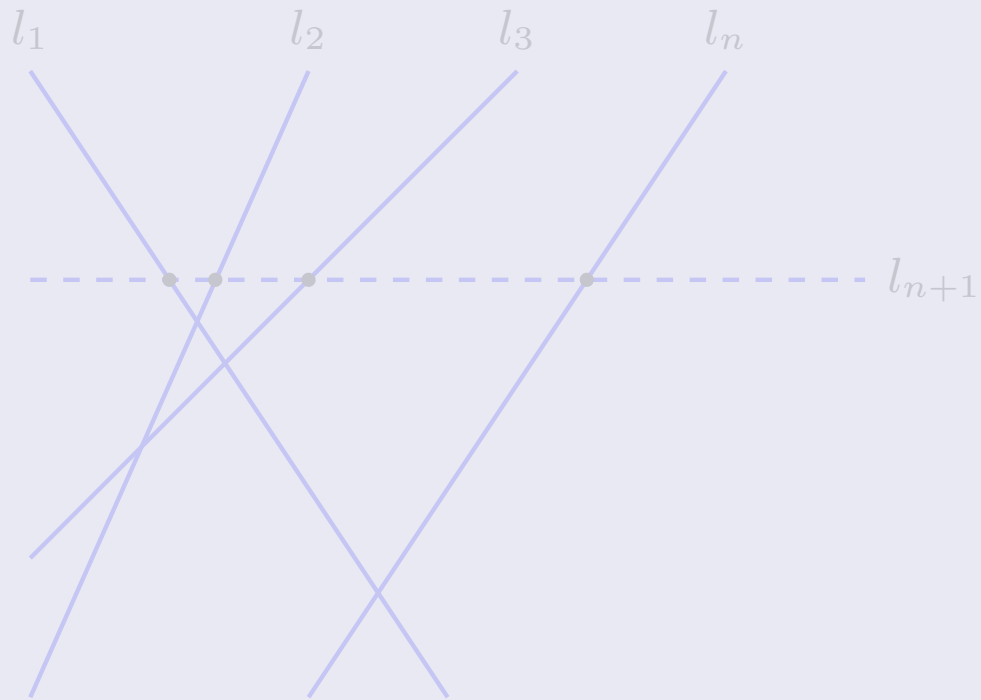

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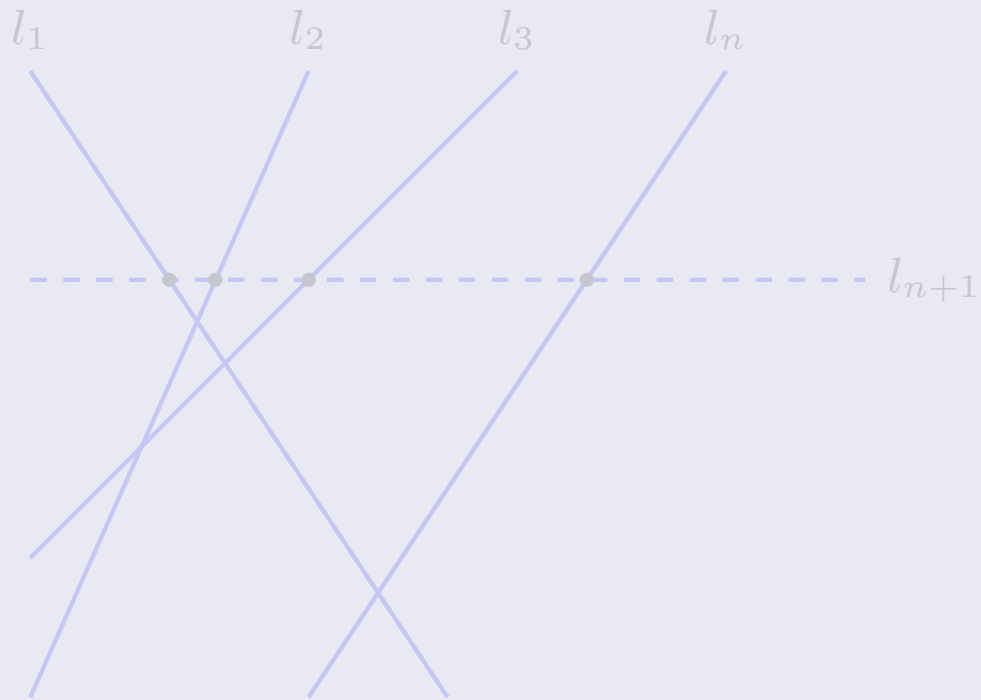

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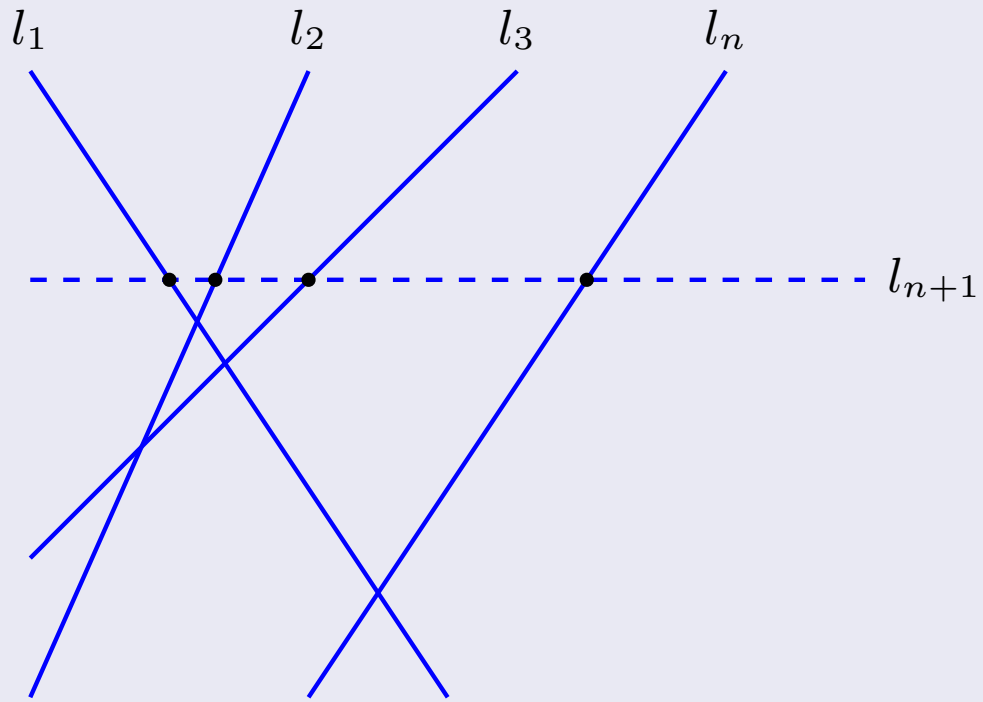

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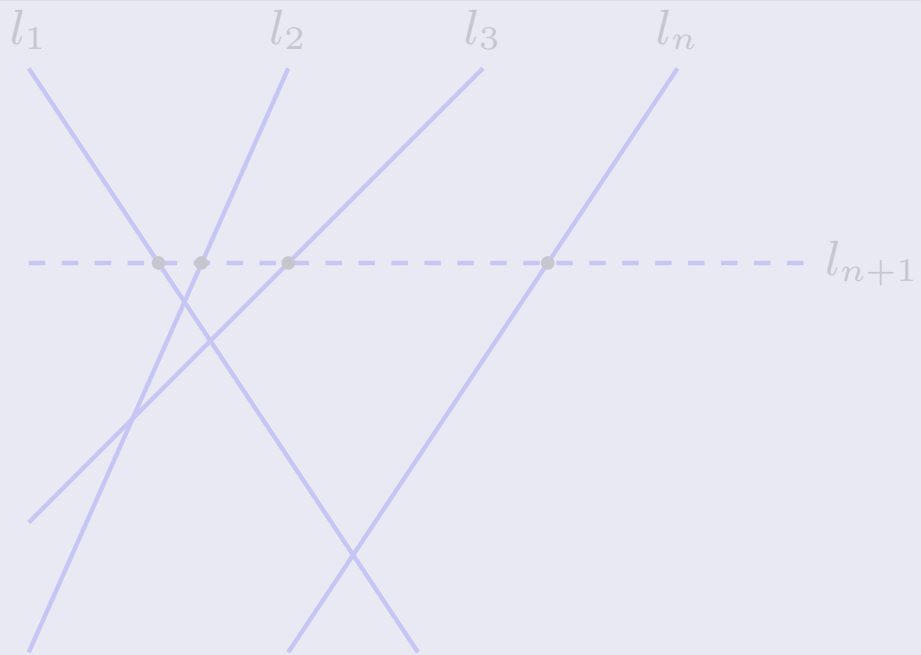

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$$A(n+1) = A(n) + n + 1, \qquad n = 1, 2, \ldots,$$

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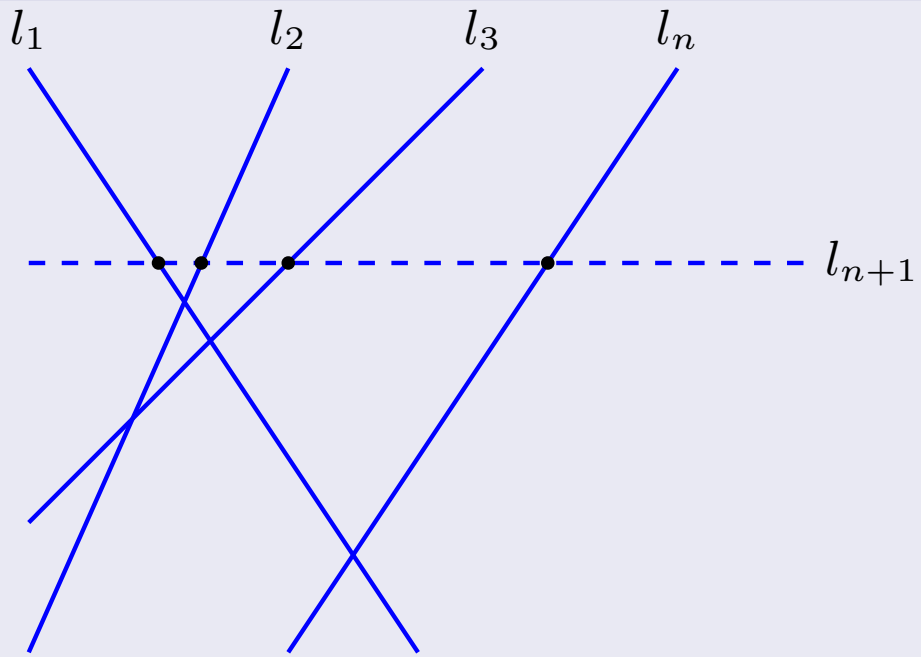

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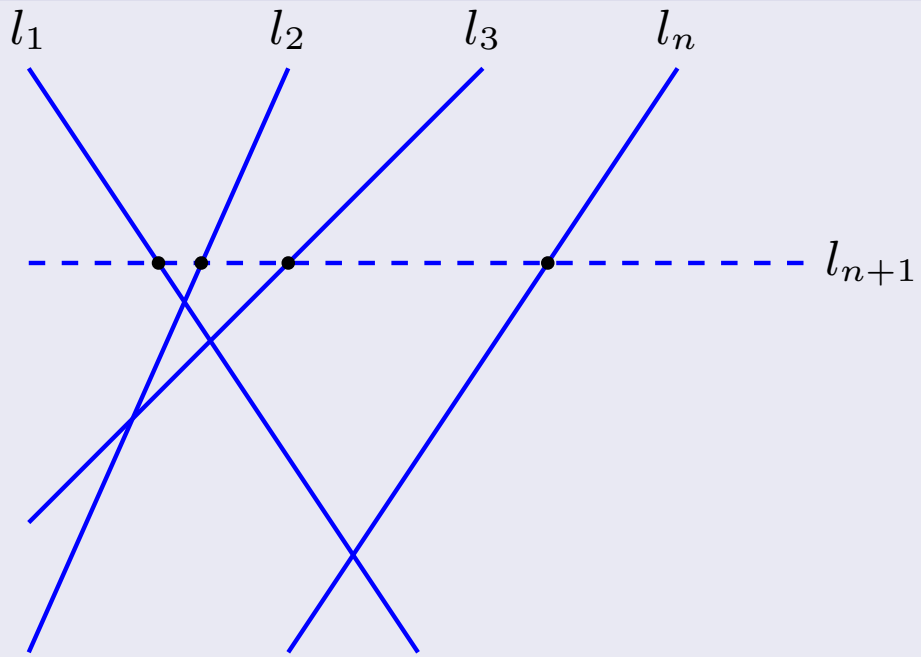

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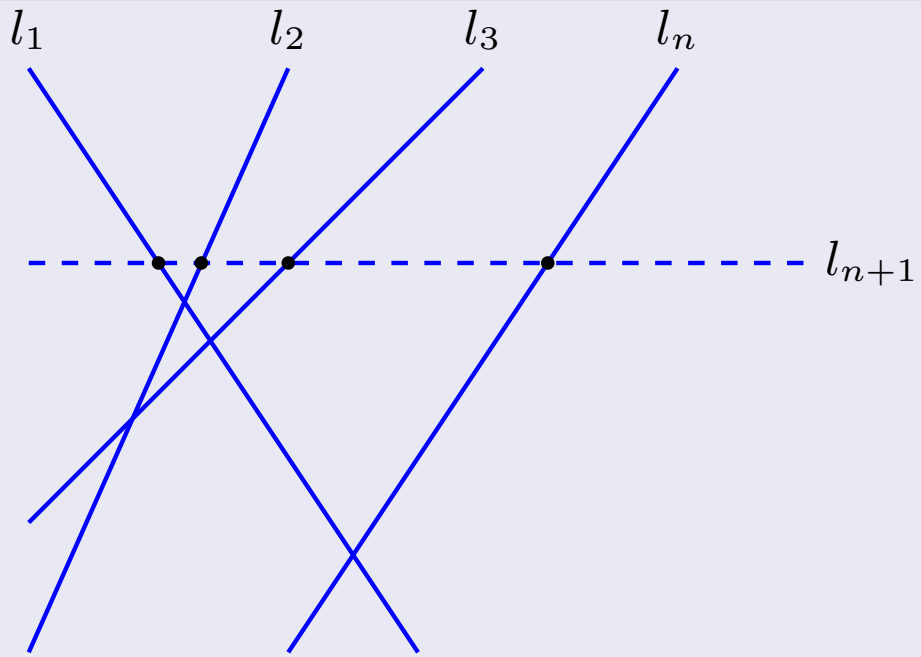

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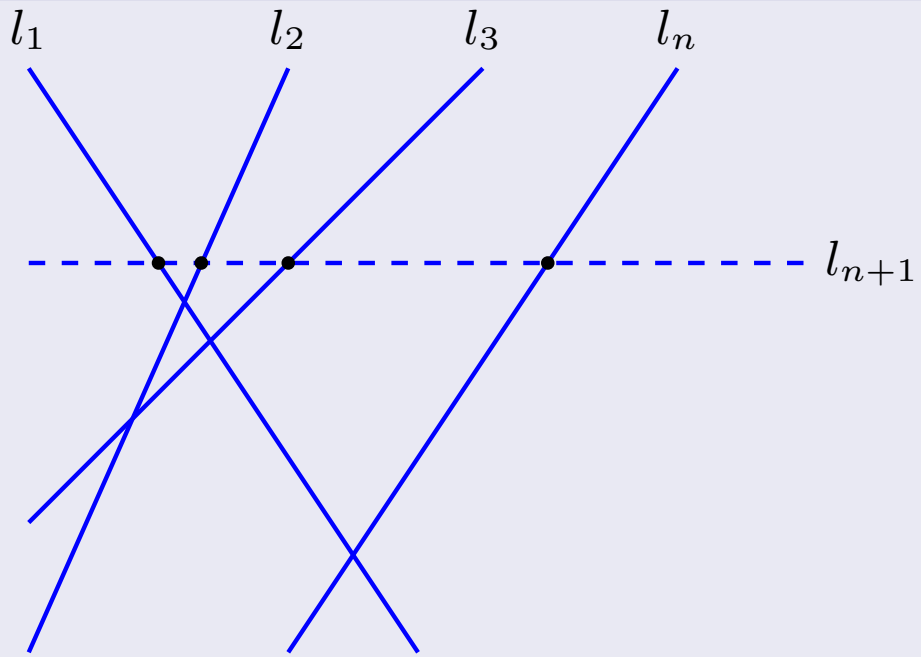

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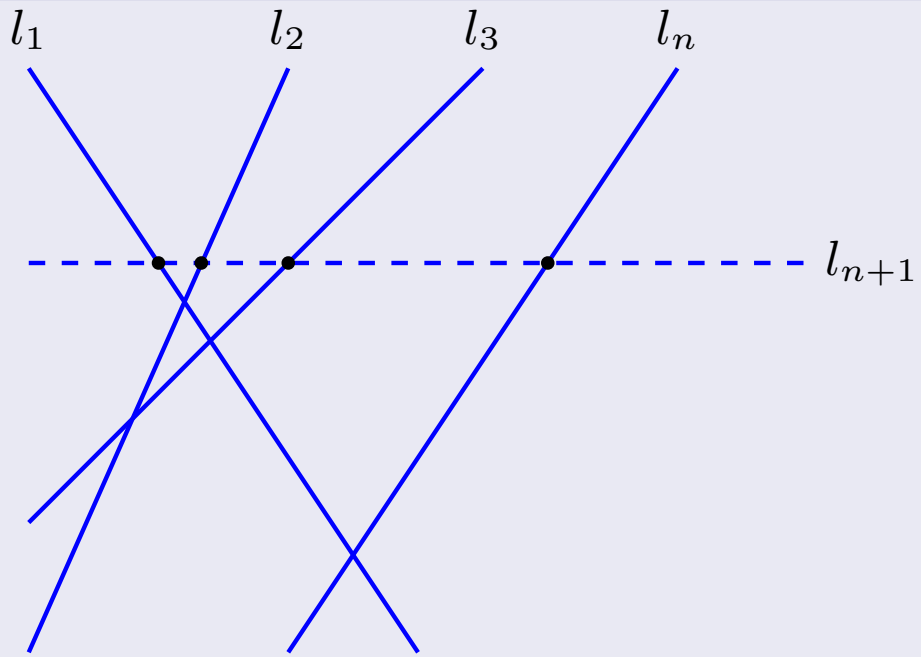

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$$A(n+1) = A(n) + n + 1, \qquad n = 1, 2, \ldots,$$

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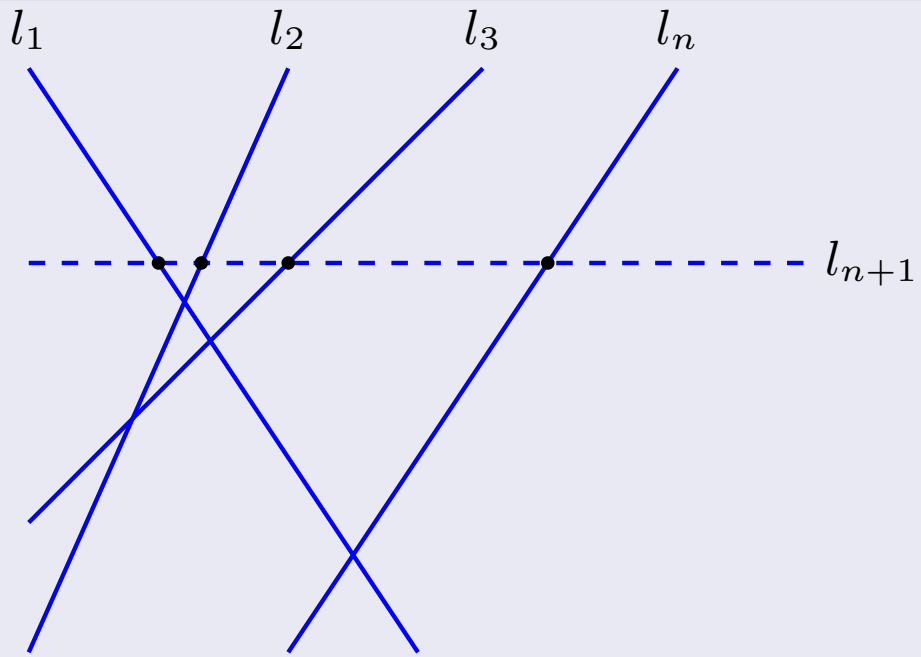

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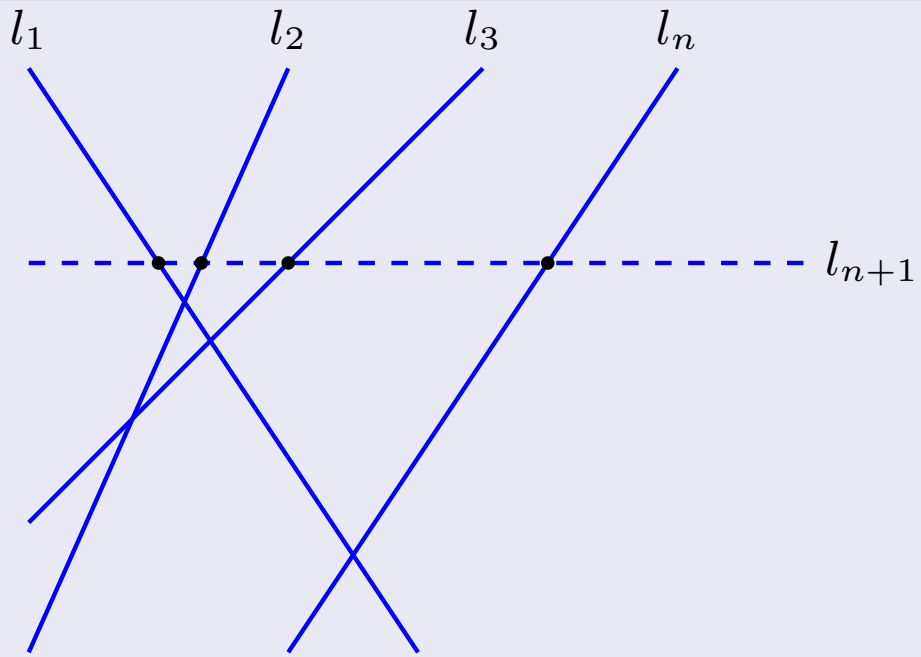

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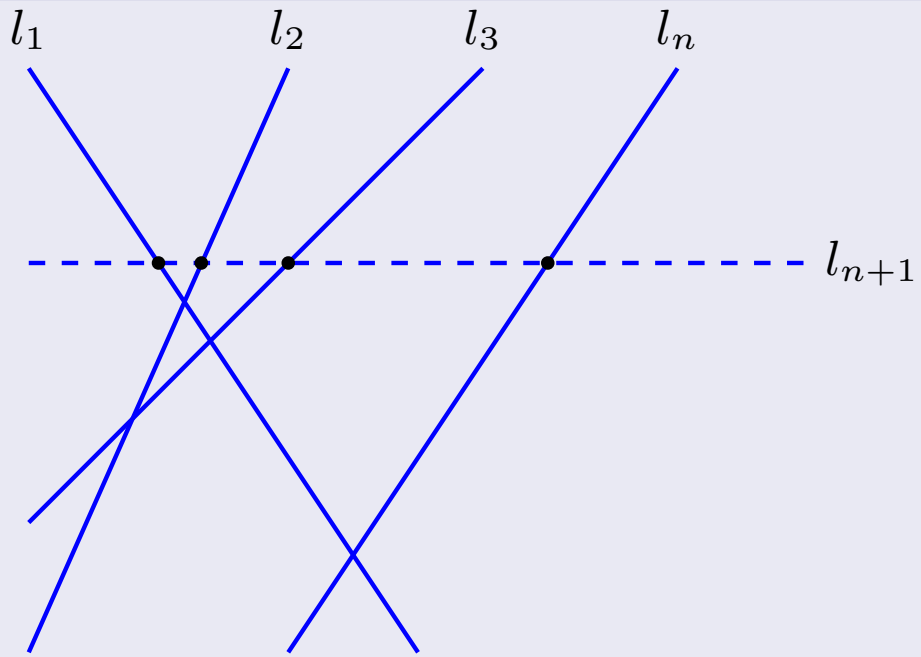

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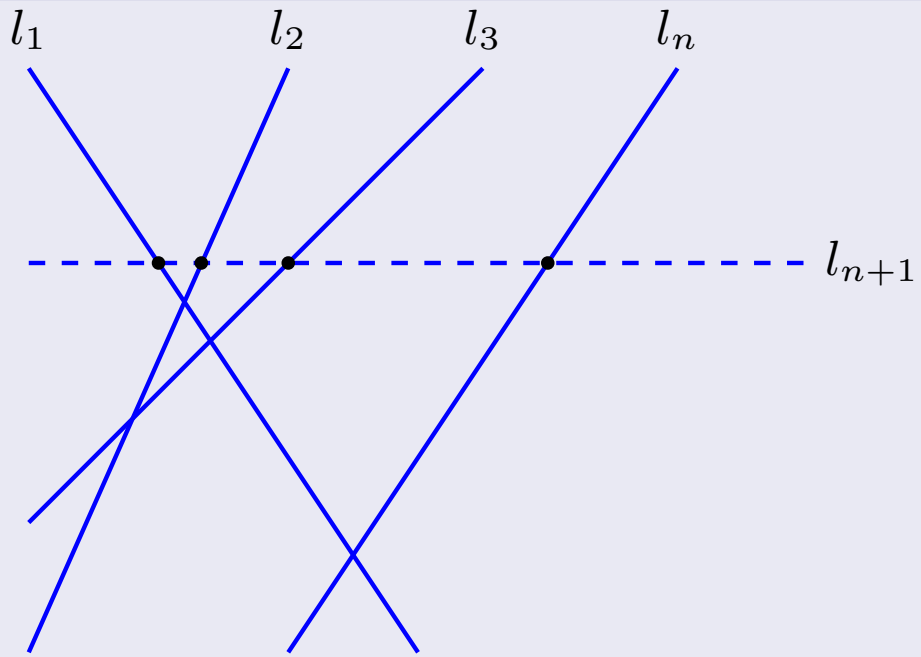

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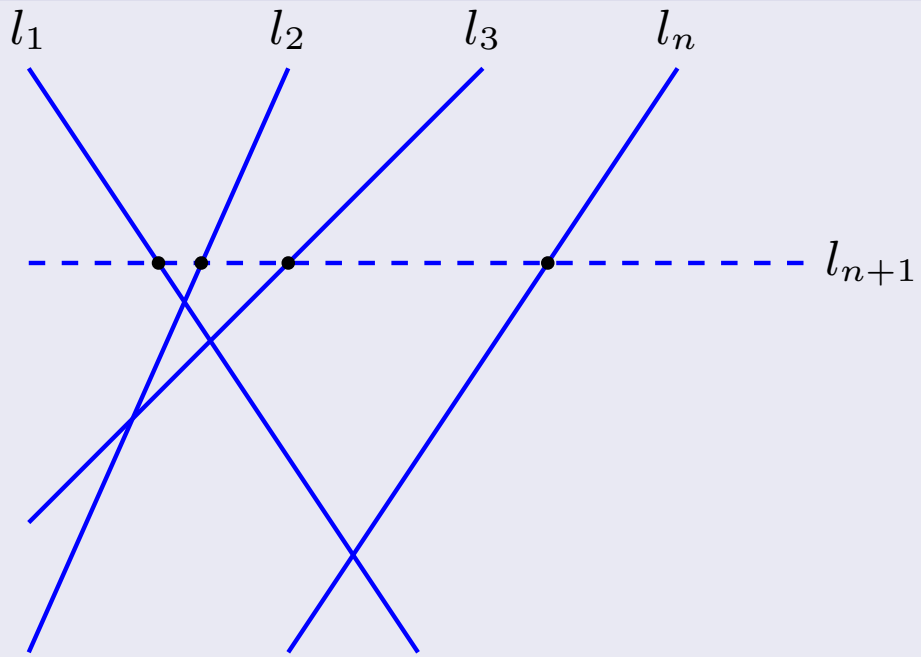

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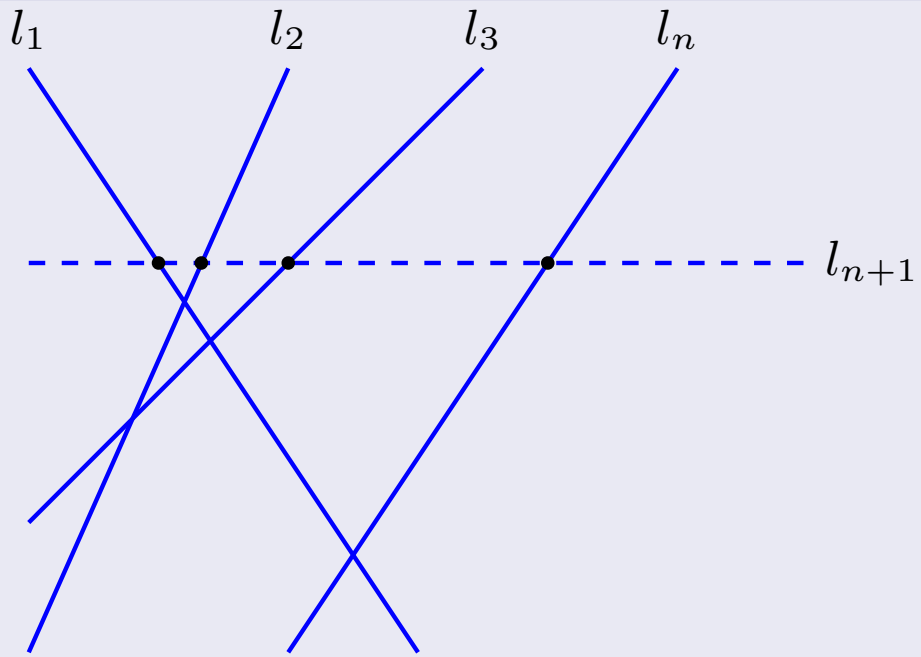

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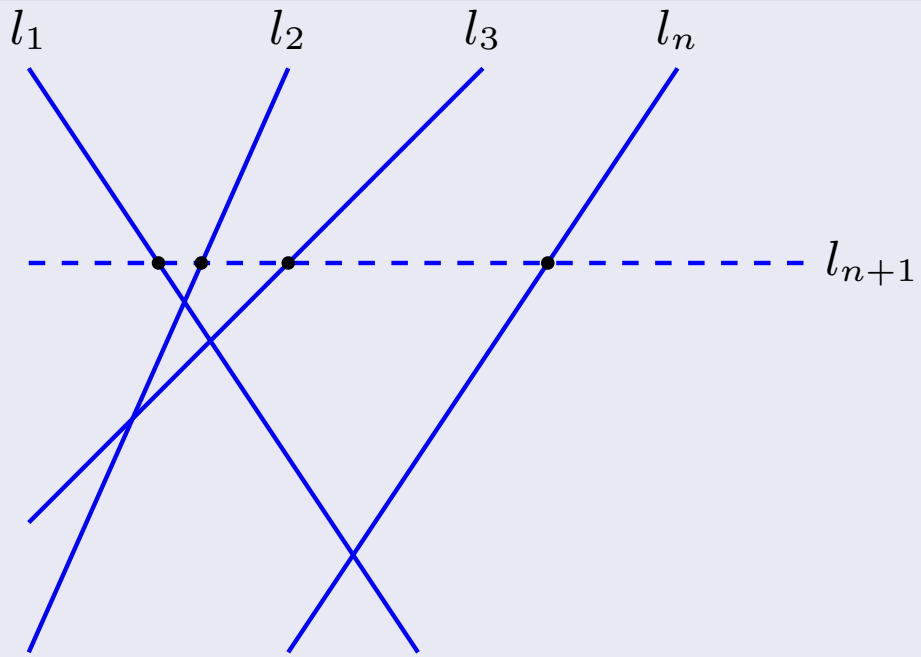

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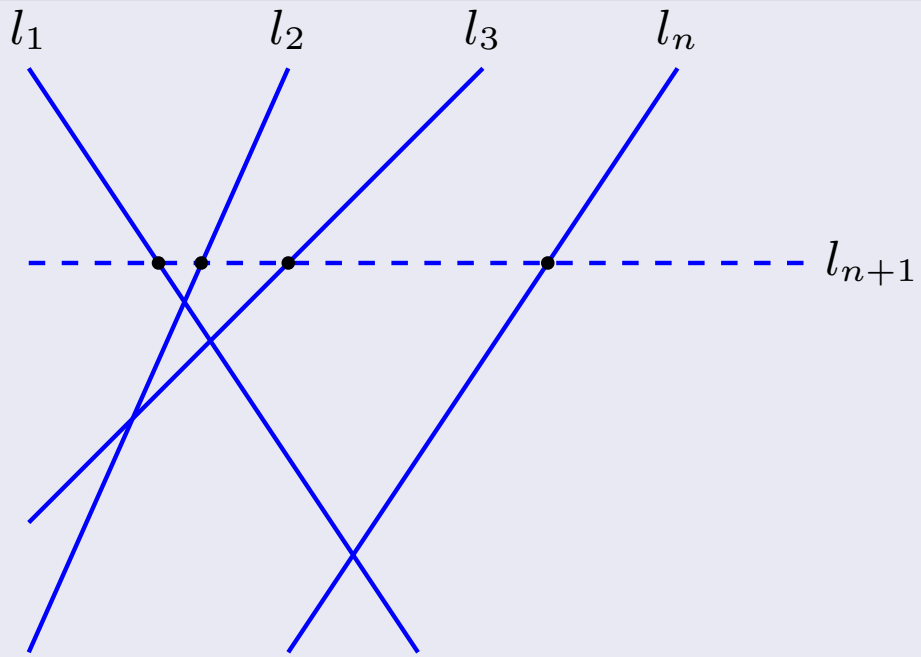

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A *rational number* is a number that can be expressed as the ratio of two integers n and m so that n and m have no a common factor. A real number that is not rational is said to be *irrational*. Show that $\sqrt{2}$ is irrational.
As in all proofs by contradiction, we assume the contrary of what we want to show. Here we assume that $\sqrt{2}$ is a rational number so that it can be written as

$$\sqrt{2} = \frac{n}{m}, \tag{5}$$

where n and m are integers without a common factor. Rearranging (5), we have that

$$2m^2 = n^2.$$

Therefore, n^2 must be even. This implies that n is even, so that we can write $n = 2k$ or

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