Formal Languages, Automata and Codes

Oleg Gutik



Lecture 1

Oleg Gutik Formal Languages, Automata and Codes. Lecture 1

In this part of preliminary lectures, we give an account of some basic notions which will be used throughout our course "Formal Languages, Automata and Codes".

$$S = \{0, 1, 2\}.$$

Ellipses are used whenever the meaning is clear. Thus, $\{a, b, \ldots, z\}$ stands for all the lowercase letters of the English alphabet, while $\{2, 4, 6, \ldots\}$ denotes the set of all positive even integers. When the need arises, we use more explicit notation, in which we write

$$S = \{i \colon i > 0, i \text{ is even}\}\tag{1}$$

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The usual set operations are *union* (U), *intersection* (\cap), and *difference* (- or \setminus) defined as

 $S_1 \cup S_2 = \{x \colon x \in S_1 \text{ or } x \in S_2\},\$ $S_1 \cap S_2 = \{x \colon x \in S_1 \text{ and } x \in S_2\},\$ $S_1 - S_2 = \{x \colon x \in S_1 \text{ and } x \notin S_2\}.$

Another basic operation is *complementation*. The *complement* of a set S, denoted by \overline{S} , consists of all elements which are not in S. To make this meaningful, we need to know what the universal set U of all possible elements is. If U is specified, then

$$\overline{S} = \{ x \colon x \in U, x \notin S \}.$$

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The following useful identities, known as *DeMorgan's laws*,

$$\overline{S_1 \cup S_2} = \overline{S_1} \cap \overline{S_2}, \tag{2}$$
$$\overline{S_1 \cap S_2} = \overline{S_1} \cup \overline{S_2}. \tag{3}$$

are needed on several occasions.

A set S_1 is said to be a *subset* of S if every element of S_1 is also an element of S. We write this as

$$S_1 \subseteq S.$$

If $S_1 \subseteq S$, but S contains an element not in S_1 , we say that S_1 is a *proper subset* of S; we write this as

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If the sets S_1 and S_2 have no common element, that is, $S_1 \cap S_2 = \emptyset$, then the sets S_1 and S_2 are said to be *disjoint*.

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If $S_1 \subseteq S$, but S contains an element not in S_1 , we say that S_1 is a *proper subset* of S; we write this as

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If the sets S_1 and S_2 have no common element, that is, $S_1 \cap S_2 = \emptyset$, then the sets S_1 and S_2 are said to be *disjoint*. A set is said to be *finite* if it contains a finite number of elements; otherwise it is infinite. The size of a finite set is the number of elements in it; this is denoted by |S|.

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If $S = \{a, b, c\}$, then its powerset is

$$2^{S} = \{ \emptyset, \{a\}, \{b\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}, \{a, b, c\} \}.$$

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A given set normally has many subsets. The set of all subsets of a set S is called the *powerset* of S and is denoted by 2^S . Observe that 2^S is a set of sets.

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Let $S_1 = \{2, 4\}$ and $S_2 = \{2, 3, 5, 6\}$. Then

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$$S_1 \times S_2 \times \cdots \times S_n = \{(x_1, x_2, \ldots, x_n) \colon x_i \in S_i\}.$$

- 1) the subsets S_1, S_2, \dots, S_n are mutually disjoint;
- 2) $S_1 \cup S_2 \cup \cdots \cup S_n = S;$
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A set can be divided by separating it into a number of subsets. Suppose that S_1, S_2, \ldots, S_n are subsets of a given set S and that the following holds:

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- 3) every of S_i is nonempty.

Then S_1, S_2, \ldots, S_n is called a *partition* of S.

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In many applications, the domain and range of the functions involved are in the set of positive integers. Furthermore, we are often interested only in the behavior of these functions as their arguments become very large. In such cases an understanding of the growth rates may suffice and a common order of magnitude notation can be used. Let f(n) and g(n) be functions whose domain is a subset of the positive integers. If there exists a positive constant c such that for all sufficiently large n

 $f(n) \le c|g(n)|,$

we say that f has order at most g. We write this as $f(n) = O(g(n)). \label{eq:generalized}$

lf

 $|f(n)| \ge c|g(n)|,$

then f has order at least g, for which we use $f(n) = \Omega(g(n))$

Finally, if there exist constants c_1 and c_2 such that $c_1|g(n)| \le |f(n)| \le c_2|g(n)|$

f and g have the same order of magnitude, expressed as $f(n) = \Theta(g(n)).$

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Oleg Gutik Formal Languages, Automata and Codes. Lecture 1

Example 1.3

_et

$$f(n) = 2n^2 + 3n,$$

$$g(n) = n^3,$$

$$h(n) = 10n^2 + 100$$

Then

f(n) = O(g(n)), $g(n) = \Omega(h(n)),$ $f(n) = \Theta(h(n)).$

In order-of-magnitude notation, the symbol = should not be interpreted as equality and order-of-magnitude expressions cannot be treated like ordinary expressions. Manipulations such as

$$O(n) + O(n) = 2O(n)$$

are not sensible and can lead to incorrect conclusions. Still, if used properly, the order-of-magnitude arguments can be effective, as we will see in later lectures.

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where x_i is an element in the domain of the function, and y_i is the corresponding value in its range. For such a set to define a function, each x_i can occur at most once as the first element of a pair. If this is not satisfied, the set is called a *relation*. Relations are more general than functions: In a function each element of the domain has exactly one associated element in the range; in a relation there may be several such elements in the range.

One kind of relation is that of *equivalence*, a generalization of the concept of equality (identity). To indicate that a pair (x, y) is in an equivalence relation, we write

 $x \equiv y$.

A relation denoted by \equiv is considered an equivalence if it satisfies three rules: the reflexivity rule

$$x \equiv x$$
 for all x ;

the symmetry rule

if $x \equiv y$, then $y \equiv x$;

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where x_i is an element in the domain of the function, and y_i is the corresponding value in its range. For such a set to define a function, each x_i can occur at most once as the first element of a pair. If this is not satisfied, the set is called a *relation*. Relations are more general than functions: In a function each element of the domain has exactly one associated element in the range; in a relation there may be several such elements in the range.

One kind of relation is that of *equivalence*, a generalization of the concept of equality (identity). To indicate that a pair (x,y) is in an equivalence relation, we write

 $x \equiv y$.

A relation denoted by \equiv is considered an equivalence if it satisfies three rules: the reflexivity rule

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if $x \equiv y$, then $y \equiv x$;

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 and $y \equiv z$, then $x \equiv z$.

On the set of nonnegative integers, we can define a relation

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if and only if

 $x \mod 3 \equiv y \mod 3.$

Then $2 \equiv 5$, $12 \equiv 0$, and $0 \equiv 36$. Clearly this is an equivalence relation, as it satisfies reflexivity, symmetry, and transitivity.

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1.1 MATHEMATICAL PRELIMINARIES AND NOTATION: Graphs and Trees

A graph is a construct consisting of two finite sets, the set

 $V = \{v_1, v_2, \dots, v_n\}$ of vertices and the set $E = \{e_1, e_2, \dots, e_m\}$ of edges. Each edge is a pair of vertices from V, for instance,

 $e_i = (v_j, v_k)$

is an edge from v_j to v_k . We say that the edge e_i is an *outgoing edge* for v_j and an *incoming edge* for v_k . Such a construct is actually a directed graph (digraph), since we associate a direction (from v_j to v_k) with each edge. Graphs may be labeled, a label being a name or other information associated with parts of the graph. Both vertices and edges may be labeled. Graphs are conveniently visualized by diagrams in which the vertices are represented as circles and the edges as lines with arrows connecting the vertices. The graph with vertices $\{v_1, v_2, v_3\}$ and edges $\{(v_1, v_3), (v_3, v_1), (v_3, v_2), (v_3, v_3)\}$ is depicted in the following Figure.



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A sequence of edges $(v_i, v_j), (v_j, v_k), \dots, (v_m, v_n)$ is said to be a *walk* from v_i to v_n . The *length of a walk* is the total number of edges traversed in going from the initial vertex to the final one. A walk in which no edge is repeated is said to be a *path*; a path is *simple* if no vertex is repeated. A walk from v_i to itself with no repeated edges is called a *cycle with base* v_i . If no vertices other than the base are repeated in a cycle, then it is said to be *simple*. In the Figure, $(v_1, v_3), (v_3, v_2)$ is a simple path from v_1 to v_2 .



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On several occasions, we will refer to an algorithm for finding all simple paths between two given vertices (or all simple cycles based on a vertex). If we do not concern ourselves with efficiency, we can use the following obvious method. Starting from the given vertex, say v_i , list all outgoing edges $(v_i, v_k), (v_i, v_l),$ At this point, we have all paths of length one starting at v_i . For all vertices v_k, v_l, \ldots so reached, we list all outgoing edges as long as they do not lead to any vertex already used in the path we are constructing. After we do this, we will have all simple paths of length two originating at v_i . We continue this until all possibilities are accounted for. Since there are only a finite number of vertices, we will eventually list all simple paths beginning at v_i . From these we select those ending at the desired vertex. On several occasions, we will refer to an algorithm for finding all simple paths between two given vertices (or all simple cycles based on a vertex). If we do not concern ourselves with efficiency, we can use the following obvious method. Starting from the given vertex, say v_i , list all outgoing edges $(v_i, v_k), (v_i, v_l),$ \ldots At this point, we have all paths of length one starting at v_i . For all vertices v_k, v_l, \ldots so reached, we list all outgoing edges as long as they do not lead to any vertex already used in the path we are constructing. After we do this, we will have all simple paths of length two originating at v_i . We continue this until all possibilities are accounted for. Since there are only a finite number of vertices, we will eventually list all simple paths beginning at v_i . From these we select those ending at the desired vertex. On several occasions, we will refer to an algorithm for finding all simple paths between two given vertices (or all simple cycles based on a vertex). If we do not concern ourselves with efficiency, we can use the following obvious method. Starting from the given vertex, say v_i , list all outgoing edges $(v_i, v_k), (v_i, v_l),$ At this point, we have all paths of length one starting at v_i . For all vertices v_k, v_l, \ldots so reached, we list all outgoing edges as long as they do not lead to any vertex already used in the path we are constructing. After we do this, we will have all simple paths of length two originating at v_i . We continue this until all possibilities are accounted for. Since there are only a finite number of vertices, we will eventually list all simple paths beginning at v_i . From these we select those ending at the desired vertex.

Trees are a particular type of graphs. A *tree* is a directed graph that has no cycles and that has one distinct vertex, called the *root*, such that there is exactly one path from the root to every other vertex. This definition implies that the root has no incoming edges and that there are some vertices without outgoing edges. These are called the *leaves of the tree*. If there is an edge from v_i to v_j , then v_i is said to be the *parent* of v_j , and v_j the *child* of v_i . The *level associated with each vertex* is the number of edges in the path from the root to the vertex. The *height* of the tree is the largest level number of any vertex. These terms are illustrated in the Figure.



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Induction is a technique by which the truth of a number of statements can be inferred from the truth of a few specific instances. Suppose we have a sequence of statements P_1, P_2, \ldots we want to prove to be true. Furthermore, suppose also that the following holds:

- 1. For some $k\geq 1$, we know that P_1,P_2,\ldots,P_k are true.
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The starting statements P_1, P_2, \ldots, P_k are called the basis of the induction. The step connecting P_n with P_{n+1} is called the *inductive step*. The inductive step is generally made easier by the inductive assumption that P_1, P_2, \ldots, P_n are true, then argue that the truth of these statements guarantees the truth of P_{n+1} . In a formal inductive argument, we show all three parts explicitly.

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Example 1.5

A binary tree is a tree in which no parent can have more than two children. Prove that a binary tree of height n has at most 2^n leaves. **Proof**: If we denote the maximum number of leaves of a binary tree of height n by l(n), then we want to show that $l(n) \leq 2^n$. **Basis**: Clearly $l(0) = 1 = 2^0$, because a tree of height 0 can have no nodes other than the root, that is, it has at most one leaf. **Inductive Assumption**:

$$l(i) \le 2^i, \text{ for } i = 0, 1, \dots, n.$$
 (4)

Inductive Step: To get a binary tree of height n + 1 from one of height n, we can create, at most, two leaves in place of each previous one. Therefore,

l(n+1) = 2l(n).

Now, using the inductive assumption, we get that

$$l(n+1) \le 2 \cdot 2^n = 2^{n+1}.$$

Thus, if our claim is true for n, it must also be true for n + 1. Since n can be any number, the statement must be true for all n.

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Example 1.6

A set l_1, l_2, \ldots, l_n of mutually intersecting straight lines divides the plane into a number of separated regions. A single line divides the plane into two parts, two lines generate four regions, three lines make seven regions, and so on. This is easily checked visually for up to three lines, but as the number of lines increases it becomes difficult to spot a pattern. Let us try to solve this problem recursively.

Look at the Figure to see what happens if we add a new line l_{n+1} to existing n lines.



Oleg Gutik Formal Languages, Automata and Codes. Lecture 1

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The region to the left of l_1 is divided into two new regions, so is the region to the left of l_2 , and so on until we get to the last line. At the last line, the region to the right of l_n is also divided. Each of the n intersections then generates one new region, with one extra at the end. So, if we let A(n) denote the number of regions generated by n lines, we see that

$$A(n+1) = A(n) + n + 1, \qquad n = 1, 2, \dots,$$



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Example 1.7

A *rational number* is a number that can be expressed as the ratio of two integers n and m so that n and m have no a common factor. A real number that is not rational is said to be *irrational*. Show that $\sqrt{2}$ is irrational. As in all proofs by contradiction, we assume the contrary of what we want to show. Here we assume that $\sqrt{2}$ is a rational number so that it can be written as

$$\sqrt{2} = \frac{n}{m},\tag{5}$$

where n and m are integers without a common factor. Rearranging (5), we have that

$$2m^2 = n^2.$$

Therefore, n^2 must be even. This implies that n is even, so that we can write n=2k or

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